

Lecture 1

*Lecturer: Yair Bartal**Scribe: Michael Schapira*

1 MAX-SAT Continued

We will begin this lecture by filling in some of the details regarding the algorithm for MAX-SAT we presented in the previous lecture. We shall then show how this algorithm can be derandomized. Let us begin with a short reminder: The algorithm comprises two sub-algorithms. The first sub-algorithm simply guesses the assignment of each variable. The expectation that this algorithm satisfies clause j (of length k) is clearly $E_{first}[c_j] = 1 - (1 - \frac{1}{2})^k$ (let $\alpha_k = 1 - (1 - \frac{1}{2})^k$). The linearity of expectation guarantees this approximation for the entire boolean formula. The second algorithm (we shall refer to as GW) is such that $E_{second}[c_j] \geq \beta_k z_j$ (with $\beta_k = 1 - (1 - \frac{1}{k})^k$).

We shall show that by randomly picking one of the two algorithms we manage to get a good approximation ratio. The intuition for this is that one gets better as k increases and the other gets better as k decreases. The expectation that clause j is satisfied by this new algorithm is $E[c_j] = \frac{1}{2}(\alpha_k + \beta_k)z_j$. We wish to show that $E[c_j] \geq \frac{3}{4}z_j$. Hence, it suffices to show that $\alpha_k + \beta_k \geq \frac{3}{2}$ for all values of k . One can easily verify that this is indeed correct (by assigning $k = 1, 2, 3$).

Now that we have designed a randomized algorithm with a good expectation of success, we shall show how it can be converted into an algorithm that succeeds with high probability. Consider a minimization problem. Let A be an algorithm, and I be an instance of the problem, such that $E[A(I)] < \alpha OPT(I)$. According to the Markov bound:

$$Pr[X \geq tE[X]] \leq \frac{1}{t}$$

Hence:

$$Pr[A(I) > (1 + \delta)\alpha OPT(I)] \leq \frac{1}{1 + \delta}$$

And so we have that by repeating our algorithm m times the probability of failure is $\leq (\frac{1}{1+\delta})^m$. For $m = O(\frac{1}{\delta} \log n)$ we have that the probability of failure is polynomially low (in n).

We now turn to derandomizing the MAX-SAT algorithm. We do this using the conditional expectation technique. We know that the randomized algorithm we have has an expectation of success of at least $\frac{4}{3}$ of the optimal solution. Define some arbitrary order on the boolean

variables x_1, \dots, x_n . We shall define a vertex (a_1, \dots, a_l) for every $1 \leq l \leq n$ and such that $a_i \in \{0, 1\}$. This vertex corresponds to the instance of the problem we get if assign x_i the value of a_i for every $1 \leq i \leq l$. Observe that for every such vertex v we can compute the expectation of the number of satisfied clauses (given the algorithm) for the instance represented by v , in polynomial time. We shall denote this expectation by E_v .

We shall now present the simple deterministic algorithm for MAX-SAT.

- Start with $v = (\emptyset)$.
- While the number of coordinates in v is smaller than n perform the following step: if $v = (a_1, \dots, a_l)$, Let $v_0 = ((a_1, \dots, a_l, 0))$ and $v_1 = ((a_1, \dots, a_l, 1))$. Assign $v = \operatorname{argmax}_{i \in \{0, 1\}} E_{v_i}$.

To see why this algorithm let us start by considering the first step. $v = (\emptyset)$, and so we know that E_v is at least a $\frac{3}{4}$ fraction of the optimal solution (we are guaranteed this by the approximation ration of the algorithm). Assume that the randomized algorithm chooses v_0 with probability p_0 and v_1 with probability p_1 . Then, $E_v = p_0 E_{v_0} + p_1 E_{v_1} \leq \max_i E_{v_i}$. And so, by choosing the v_i that maximizes the expectation E_{v_i} we are still guaranteed a good approximation. We can now repeat this step over and over again without reducing the value of the guaranteed expectation.

2 On Chebyshev and Chernoff Bounds

Theorem 1 (*The Chebyshev bound:*) $Pr[|X - E[X]| > t\sigma] < \frac{1}{t^2}$

Proof: Set $Y = (X - E[X])^2$ and apply the Markov bound. ■

Theorem 2 (*The Chernoff bound:*) Let X_i ($1 \leq i \leq n$) be n random variables such that $Pr[X_i = 1] = p_i$ and $Pr[X_i = 0] = 1 - p_i$. Let $X = \sum_i X_i$ and $\mu = E[X]$. Then:

$$Pr[X < (1 - \delta)\mu] < \left(\frac{e^{-\delta}}{(1 - \delta)^{(1-\delta)}}\right)^\mu < e^{-\frac{\delta^2 \mu}{2}}$$

$$Pr[X > (1 + \delta)\mu] < \left(\frac{e^\delta}{(1 + \delta)^{(1+\delta)}}\right)^\mu$$

For instance, if we were to toss a fair coin 10000 times what is the probability that we get heads in less that 4500 tosses. In this case $\mu = 5000$, $\delta = \frac{1}{10}$ and $n = 10000$, and so, by the Chernoff bound, the probability is less than e^{-25} .

Let us consider a use of of the Chebychev bound. The problem we will look at is finding the number of satisfying assignments for a DNF boolean formula. For every clause c_i with

r_i literals denote by S_i the number of satisfying assignments. Clearly, $|S_i| = 2^{n-r_i}$. And so, we denote the number of satisfying solutions for a formula f by $\#f = |\bigcup_i S_i|$. Let M be the multiset that contains the elements is all the S_i 's (including repetitions of the same elements). Obviously, $|M| = \sum_i |S_i|$. For every assignment a define $c(a)$ to be the number of clauses satisfied by a . We wish to choose a random assignment r by assigning a probability of $\frac{c(a)}{|M|}$ to every assignment a . First, we randomly choose a clause c_i with probability $\frac{|S_i|}{|M|}$. We shall now uniformly choose one of the assignments in S_i . We now have that

$$Pr[\text{assignment } a \text{ is chosen}] = \sum_{a \in S_i} \left(\frac{|S_i|}{|M|} \frac{1}{|S_i|} \right) = \frac{c(a)}{|M|}$$

For every assignment a we define a random variable $X(a)$ such that $X(a) = \frac{|M|}{c(a)}$ if a is chosen and 0 otherwise. Let $X = \sum_a X(a)$.

Lemma 3 $E[X] = \#f$

This is easy to verify. The proof of the next lemma is omitted.

Lemma 4 Let v_k be the average of k independent samples of X . Then, $\forall \epsilon > 0$,

$$Pr[|v_k - \#f| \leq \epsilon \#f] \geq \frac{3}{4}$$

.