

Data Structures – LECTURE 6

Dynamic data structures

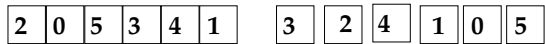
- Motivation
- Common dynamic ADTs
- Stacks, queues, lists: abstract description
- Array implementation of stacks and queues
- Linked lists
- Rooted trees
- Implementations

Data Structures, Spring 2004 © L. Jaskowicz

1

Motivation (1)

- So far, we have dealt with one type of data structure: an array. Its **length** does not change, so it is a **static** data structure. This either requires knowing the length ahead of time or waste space.
- In many cases, we would like to have a **dynamic** data structure whose length changes according to computational needs
- For this, we need a scheme that allows us to store elements in physically different order.



Data Structures, Spring 2004 © L. Jaskowicz

2

Motivation (2)

- Examples of operations:
 - **Insert**(S, k): Insert a new element
 - **Delete**(S, k): Delete an existing element
 - **Min**(S), **Max**(S): Find the element with the maximum/minimum value
 - **Successor**(S, x), **Predecessor**(S, x): Find the next/previous element
- At least one of these operations is usually expensive (takes $O(n)$ time). Can we do better?

Data Structures, Spring 2004 © L. Jaskowicz

3

Abstract Data Types –ADT

- An abstract data type is a collection of formal specifications of data-storing entities with a well designed set of operations.
- The set of operations defined with the ADT specification are the operations it “supports”.
- What is the difference between a data structure (or a class of objects) and an ADT?
 - The data structure or class is an *implementation* of the ADT to be run on a specific computer and operating system. Think of it as an abstract JAVA class. The course emphasis is on ADTs.

Data Structures, Spring 2004 © L. Jaskowicz

4

Common dynamic ADTs

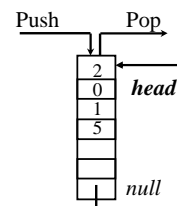
- Stacks, queues, and lists
- Nodes and pointers
- Linked lists
- Trees: rooted trees, binary search trees, red-black trees, AVL-trees, etc.
- Heaps and priority queues
- Hash tables

Data Structures, Spring 2004 © L. Jaskowicz

5

Stacks -- מחסנית

- A stack S is a linear sequence of elements to which elements x can only be inserted and deleted from the head of the list in the order they appear.
- A stack implements the Last-In-First-Out (LIFO) policy.
- The stack operations are:
 - Stack-Empty(S)
 - Pop(S)
 - Push(S, x)

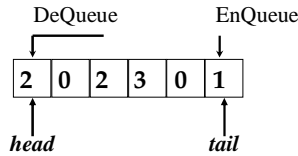


Data Structures, Spring 2004 © L. Jaskowicz

6

Queues -- תור

- A queue Q is a linear sequence of elements to which elements are inserted at the end and deleted from the beginning.
- A queue implements the First-In-First-Out (FIFO) policy.
- The queue operations are:
 - Queue-Empty(Q)
 - EnQueue(Q, x)
 - DeQueue(Q)

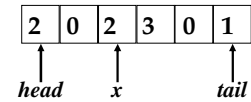


Data Structures, Spring 2004 © L. Jaskowicz

7

Lists -- רשימות

- A list L is a linear sequence of elements.
- The first element of the list is the head and the last is the tail. When both are null, the list is empty
- Each element has a predecessor and a successor
- The list operations are:
 - Successor(L, x), Predecessor(L, x)
 - List-Insert(L, x)
 - List-Delete(L, x)
 - List-Search(L, k)



Data Structures, Spring 2004 © L. Jaskowicz

8

Implementing stacks and queues

- Array implementation
 - use an array A of n elements $A[i]$, where n is the maximum number of elements expected.
 - Top(A), Head(A), and Tail(A) are array indices
 - Stack and queue operations involve index manipulation
 - Lists are not efficiently implemented with arrays
- Linked list
 - Create objects for elements as they appear
 - Do not have to know the maximum size in advance
 - Manipulate pointers

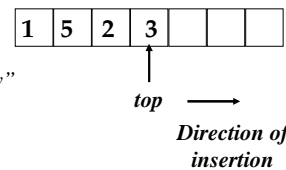
Data Structures, Spring 2004 © L. Jaskowicz

9

Stacks: array implementation

Push(S, x)

1. if $top[S] = length[S]$
2. then error "overflow"
3. $top[S] \leftarrow top[S] + 1$
4. $S[top[S]] \leftarrow x$



Pop(S)

1. if $top[S] = 0$
2. then error "underflow"
3. else $top[S] \leftarrow top[S] - 1$
4. return $S[top[S] + 1]$

Stack-Empty(S)

1. if $top[S] = 0$
2. then return true
3. else return false

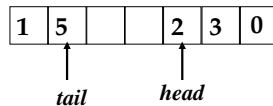
Data Structures, Spring 2004 © L. Jaskowicz

10

Queues: array implementation

Dequeue(Q)

1. $x \leftarrow Q[head[Q]]$
2. if $head[Q] = length[Q]$
3. then $head[Q] \leftarrow 1$
4. else $head[Q] \leftarrow (head[Q] + 1)_{mod\ n}$
5. return x



Enqueue(Q, x)

1. $Q[tail[Q]] \leftarrow x$
2. if $tail[Q] = length[Q]$
3. then $tail[Q] \leftarrow x$
4. else $tail[Q] \leftarrow (tail[Q] + 1)_{mod\ n}$

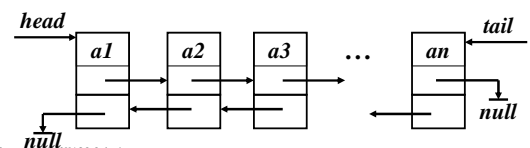
Boundary conditions omitted

Data Structures, Spring 2004 © L. Jaskowicz

11

Linked Lists -- רשימות מקושרות

- The physical and logical order of elements need not be the same; instead, use pointers to indicate where the next (previous) element is.
- By manipulating the pointers, we can insert and delete elements without having to move all the others! Lists can be singly or doubly linked.



Data Structures, Spring 2004 © L. Jaskowicz

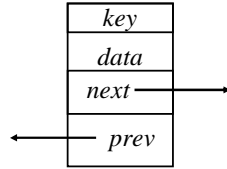
12

Nodes and pointers

- A node is an object that holds the data, a pointer to the next node and (optionally), a pointer to the previous node. If there is no next node, the pointer is to "null"

```

Class ListNode {
  Object key;
  Object data;
  ListNode next;
  ListNode prev;
}
    
```



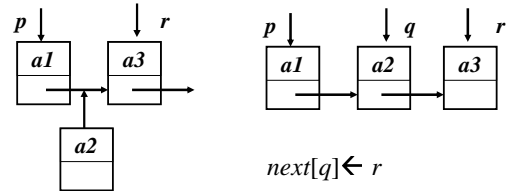
- A pointer indicates the memory address of a node
- Nodes usually occupy constant space: $\Theta(1)$

Data Structures, Spring 2004 © L. Jaskowicz

13

Example: Insertion

Insertion of a new node q between successive nodes p and r :



$next[q] \leftarrow r$

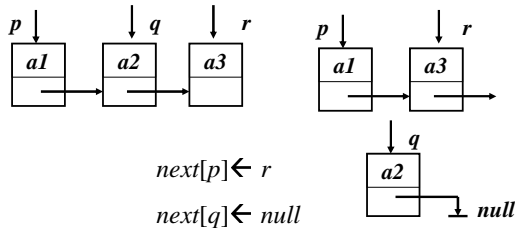
$next[p] \leftarrow q$

Data Structures, Spring 2004 © L. Jaskowicz

14

Example: Deletion

Deletion of a node q between previous node p and successor node r



$next[p] \leftarrow r$

$next[q] \leftarrow null$

Data Structures, Spring 2004 © L. Jaskowicz

15

Linked lists operations

List-Search(L, k)

- $x \leftarrow head[L]$
- while** $x \neq null$ and $key[x] \neq k$
- do** $x \leftarrow next[x]$
- return** x

List-Insert(L, x)

- $next[x] \leftarrow head[L]$
- if** $head[L] \neq null$
- then** $prev[head[L]] \leftarrow x$
- $head[L] \leftarrow x$
- $prev[x] \leftarrow null$

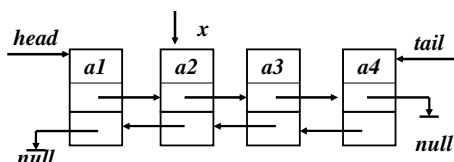
List-Delete(L, x)

- if** $prev[L] \neq null$
- then** $next[prev[x]] \leftarrow next[x]$
- else** $head[L] \leftarrow next[x]$
- if** $next[L] \neq null$
- then** $prev[next[x]] \leftarrow prev[x]$

Data Structures, Spring 2004 © L. Jaskowicz

16

Example: linked list operations



Circular lists: connect first and last elements!

Data Structures, Spring 2004 © L. Jaskowicz

17

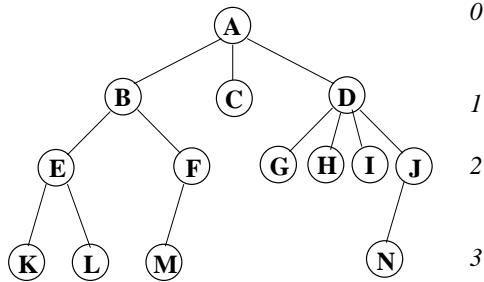
Rooted trees

- A rooted tree T is an ADT in which elements are ordered in a tree-like structure.
- A tree consists of nodes, which hold elements, and edges, which show relations between two nodes.
- There are three types of nodes: a root, internal nodes, leaf
- The tree structure is:
 - Connected: there is an edge path from the root to any other node
 - No cycles: there is only one path from the root to a node
 - Each node except the root has a single ancestor
 - Leaves have no outgoing edges
 - Internal nodes have one or more out-going edges ($= 2 \rightarrow$ binary)

Data Structures, Spring 2004 © L. Jaskowicz

18

Rooted tree: example



Data Structures, Spring 2004 © L. Jaskowicz

19

Trees terminology

- Internal nodes have a **parent** and one or more **children**.
- Nodes on the same level are **siblings** (children of the same parent)
- **Ancestor/descendent** relationships – recursive definition of parent and children.
- **Degree of a node**: number of children
- **Path**: a sequence of nodes n_1, n_2, \dots, n_k such that n_i is a parent of n_{i+1} . The path length is k .
- **Tree height**: length of the longest path from a root to a leaf.
- **Node depth**: length of the path from the root to the node.

Data Structures, Spring 2004 © L. Jaskowicz

20

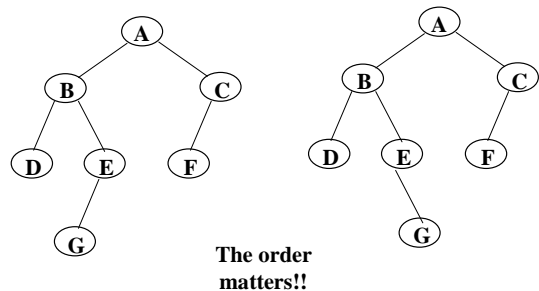
Binary trees

- A binary tree **T** is a tree whose root and internal nodes have at most two children.
- **Recursively**: a binary tree is a tree that either contains no nodes or consists of a root node, and two sub-trees (left and right) each of which is also a binary tree.

Data Structures, Spring 2004 © L. Jaskowicz

21

Binary tree: example

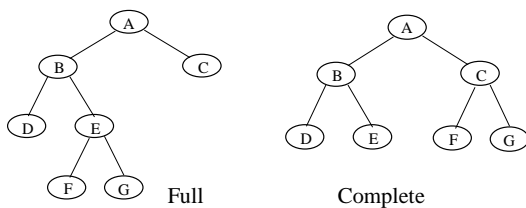


Data Structures, Spring 2004 © L. Jaskowicz

22

Full and complete trees

- Full binary tree: each node has either degree 0 (a leaf) or 2 exactly two non-empty children.
- Complete binary tree: a full binary tree in which all leaves have the same depth.



Data Structures, Spring 2004 © L. Jaskowicz

23

Properties of binary trees

- How many leaf nodes does a complete binary tree of height d have?

$$2^d$$

- What is the number of internal nodes in such a tree?

$$1+2+4+\dots+2^{d-1} = 2^d - 1 \text{ (less than half!)}$$

- What is the total number of nodes?

$$1+2+4+\dots+2^d = 2^{d+1} - 1$$

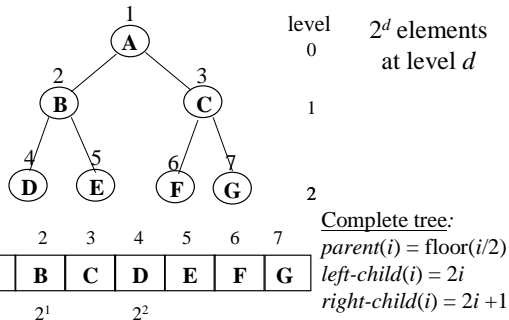
- How tall can a full/complete binary tree with n leaf nodes be?

$$(n-1)/2 \quad 2^{d+1} - 1 = n \rightarrow \log(n+1) - 1 \leq \log(n)$$

Data Structures, Spring 2004 © L. Jaskowicz

24

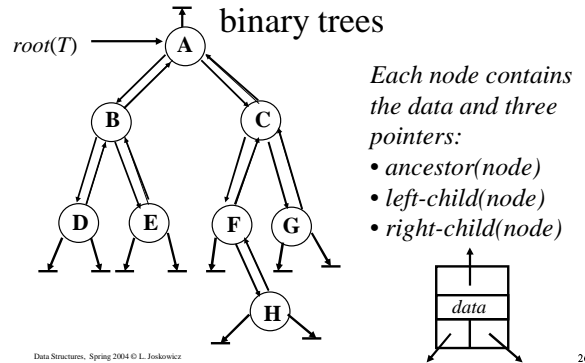
Array implementation of binary trees



Data Structures, Spring 2004 © L. Jaskowicz

25

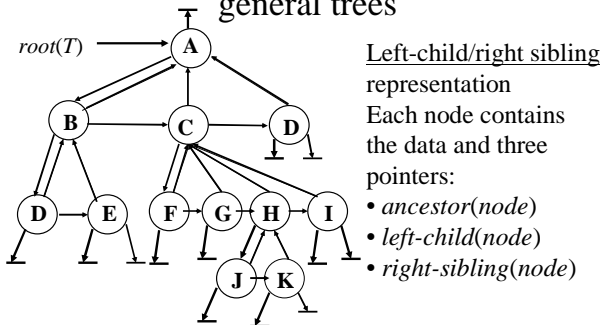
Linked list implementation of binary trees



Data Structures, Spring 2004 © L. Jaskowicz

26

Linked list implementation of general trees



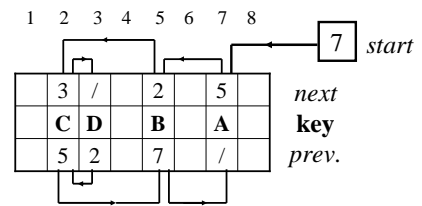
Data Structures, Spring 2004 © L. Jaskowicz

27

Implementation of pointers and objects

Multiple-array representation of objects:

Each object with k fields is represented as an array with k elements + 2 fields: $previous$ and $next$;



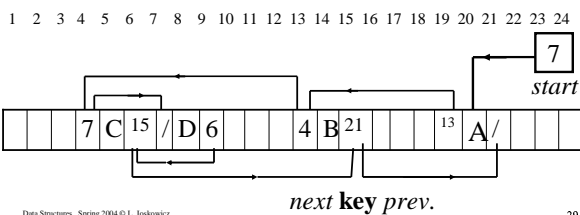
Data Structures, Spring 2004 © L. Jaskowicz

28

Implementation of pointers and objects

Single-array representation of objects:

Each object with k fields is represented with k consecutive fields 2 fields: $previous$ and $next$;



Data Structures, Spring 2004 © L. Jaskowicz

29

Memory management

- Most languages have a mechanism for allocating and freeing storage objects.
- Memory can be thought of as containing two zones: *free memory* and *used memory*.
- Allocating objects: when a new object structure is created, the next available free memory block is used
- De-allocating objects: an object becomes unused when it cannot be reached anymore. Accumulating unused objects is bad since the system can run out of memory unexpectedly.

Data Structures, Spring 2004 © L. Jaskowicz

30

Allocating and freeing objects

- Two ways to deal with unused objects:
 - the user explicitly frees (de-allocate) objects
 - the system performs “garbage collection” upon request or automatically, once in a while
- When a program terminates, its storage must be recovered (marked free) for otherwise the memory will quickly fill up.
- Keep free objects in a singly linked list managed as a stack → freeing and releasing an object takes $O(1)$.

Code for allocate and free

Allocate-Object()

1. **if** $free = null$
2. **then error** “out of space”
3. **else** $x \leftarrow free$
4. $free \leftarrow next[x]$
5. **return** x

Free-Object(x)

1. $next[x] \leftarrow free$
2. $free \leftarrow x$